

SPACE WARPS

ZOONIVERSE

Crowd-sourcing the discovery of gravitational lenses

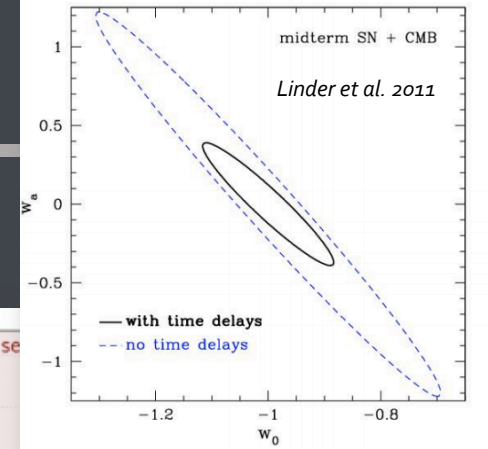
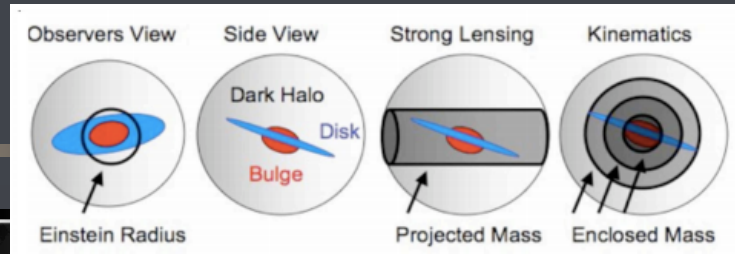
Kavli Symposium: Future Surveys and Citizen Science

15th April 2015

Aprajita Verma

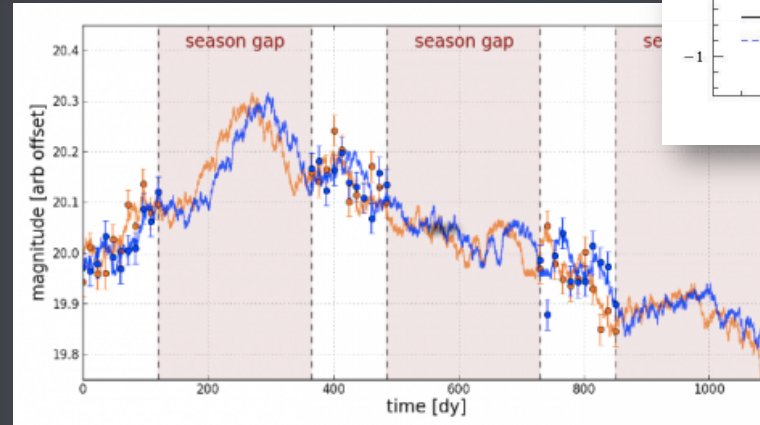
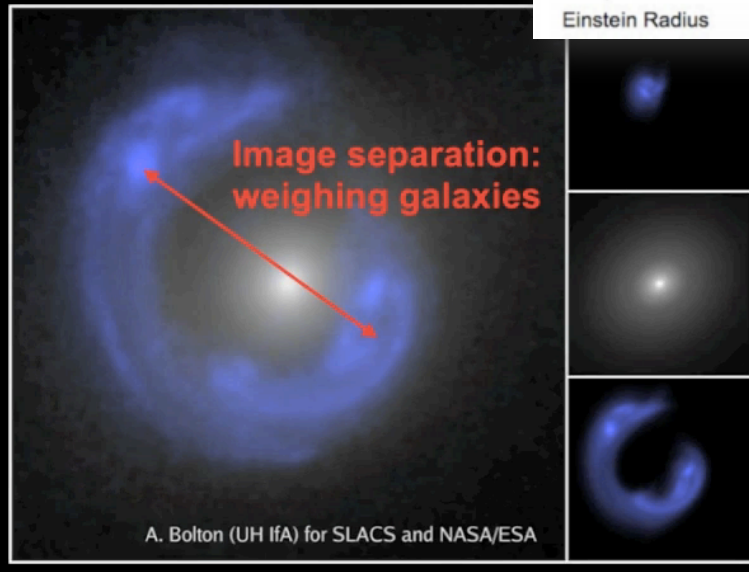
averma@astro.ox.ac.uk

Weighing galaxies

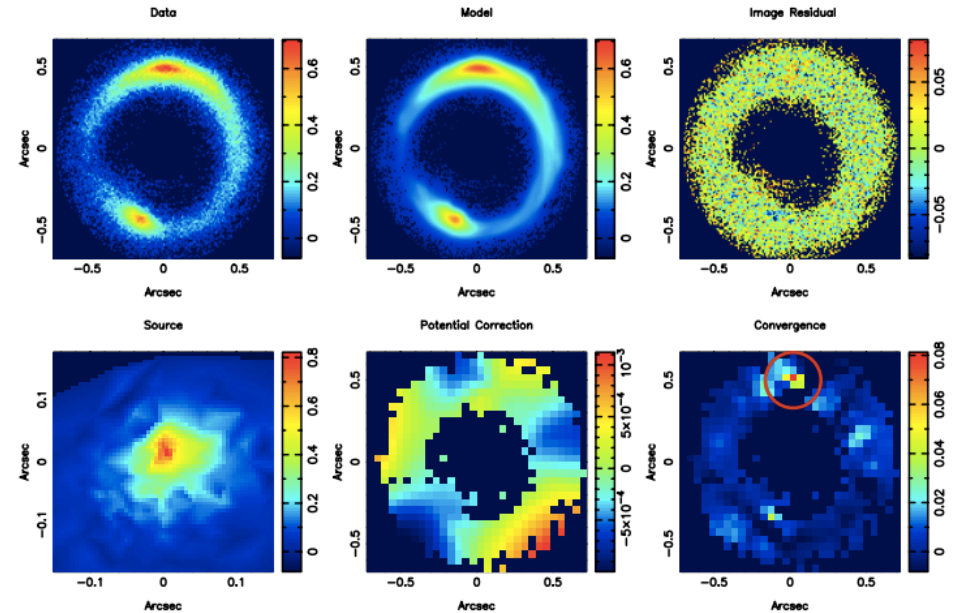


QSO/SN time delays

DM Substructure



Grid-base modeling (Vegetti & Koopmans 2009)



Lagattuta et al. 2012; Vegetti et al., 2012, Nature

Cosmic telescope

Needles in a Haystack

Strong lensing is rare

only 1 in ~ 10000 massive galaxies act as lenses

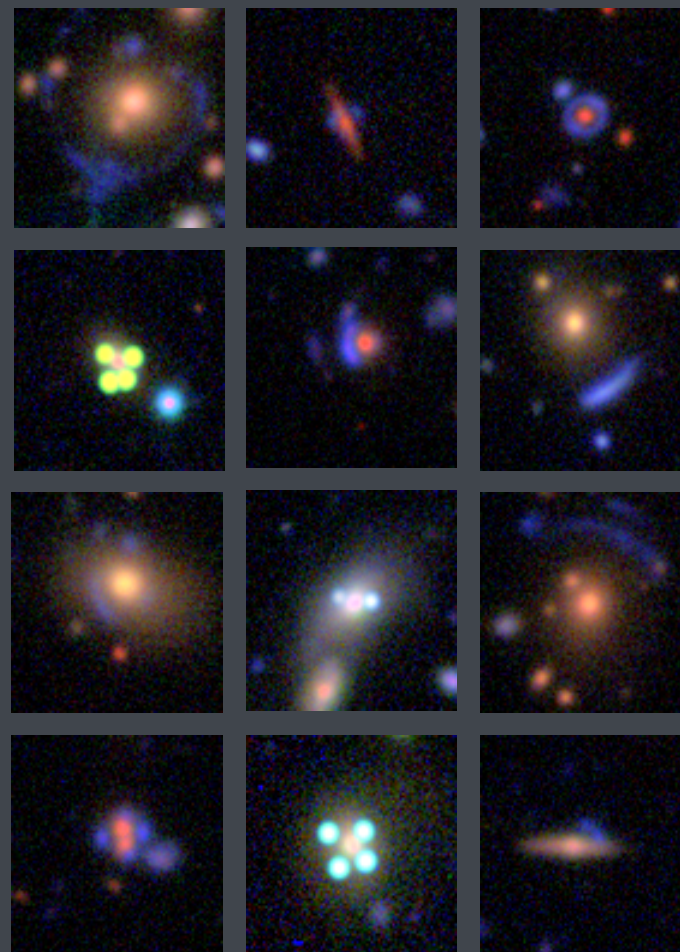
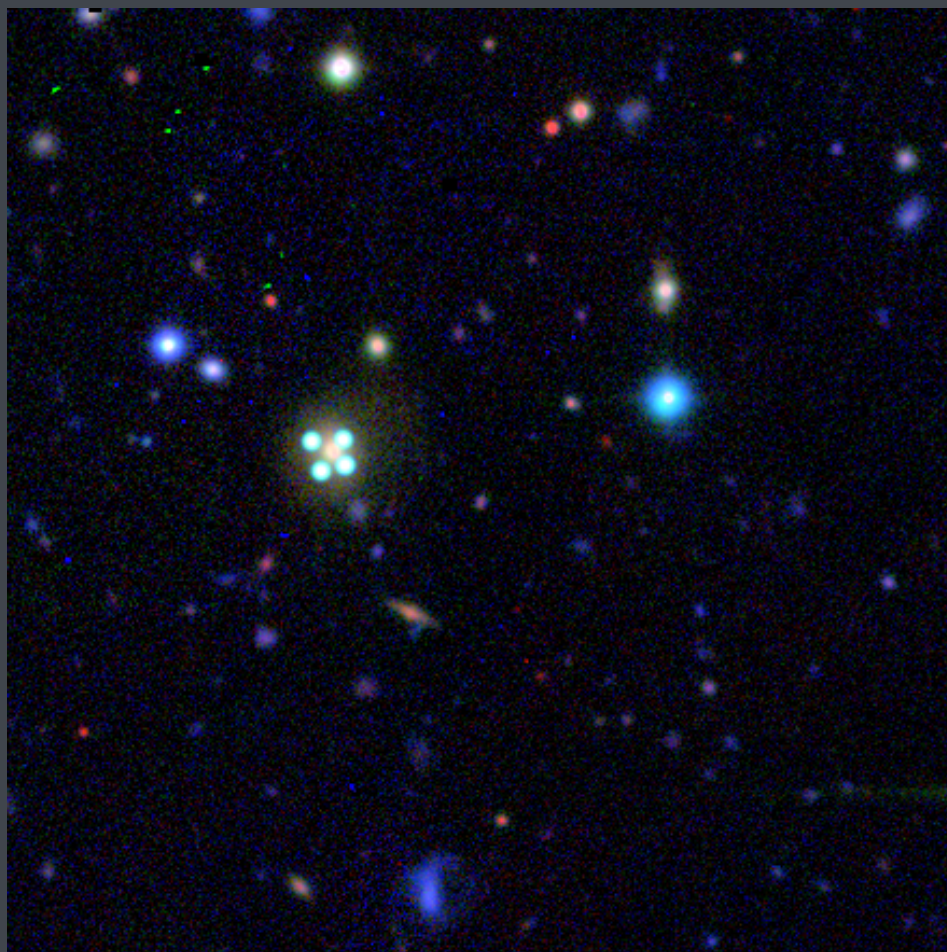
only ~ 500 strong lenses currently confirmed



Needles in a Haystack

entering an era of very large & sensitive imaging surveys

~8000 lensed AGN, 10^{4-5} galaxy-scale lenses
1000s of clusters, 100s of lensed SNe...



How will we find them?

Automated lens finding algorithms (robots) have been developed with good success



But robots might not find everything

- good at finding types of lenses (e.g. “ring-finder” “arc finder”)
- may miss low surface brightness or low separation images
- complex or “exotic” lenses



Even with “robots” in place, strong gravitational lensing research remains very labour-intensive:

- Inspection of lens candidates from robots
- Detailed modelling of individual systems



From <http://www.vanderstahl.com>

THE SOLUTION: PART 1



<http://commons.wikimedia.org>

ZOONIVERSE

We make citizen science websites so that everyone can be part of real research online

THE SOLUTION: PART 2

condorwatch.org

Help save the California condor!



All

Space

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Humanities

Nature

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Space

www.zooniverse.org

Sort by



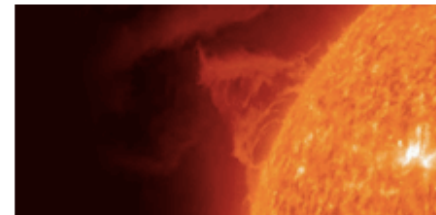
How do galaxies form?

NASA's Hubble Space Telescope archive provides hundreds of thousands of galaxy images.



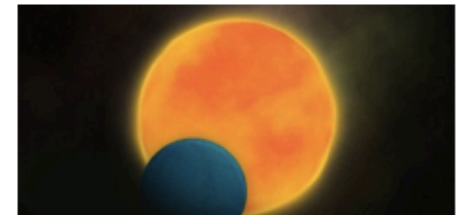
Explore the surface of the Moon

We hope to study the lunar surface in unprecedented detail.



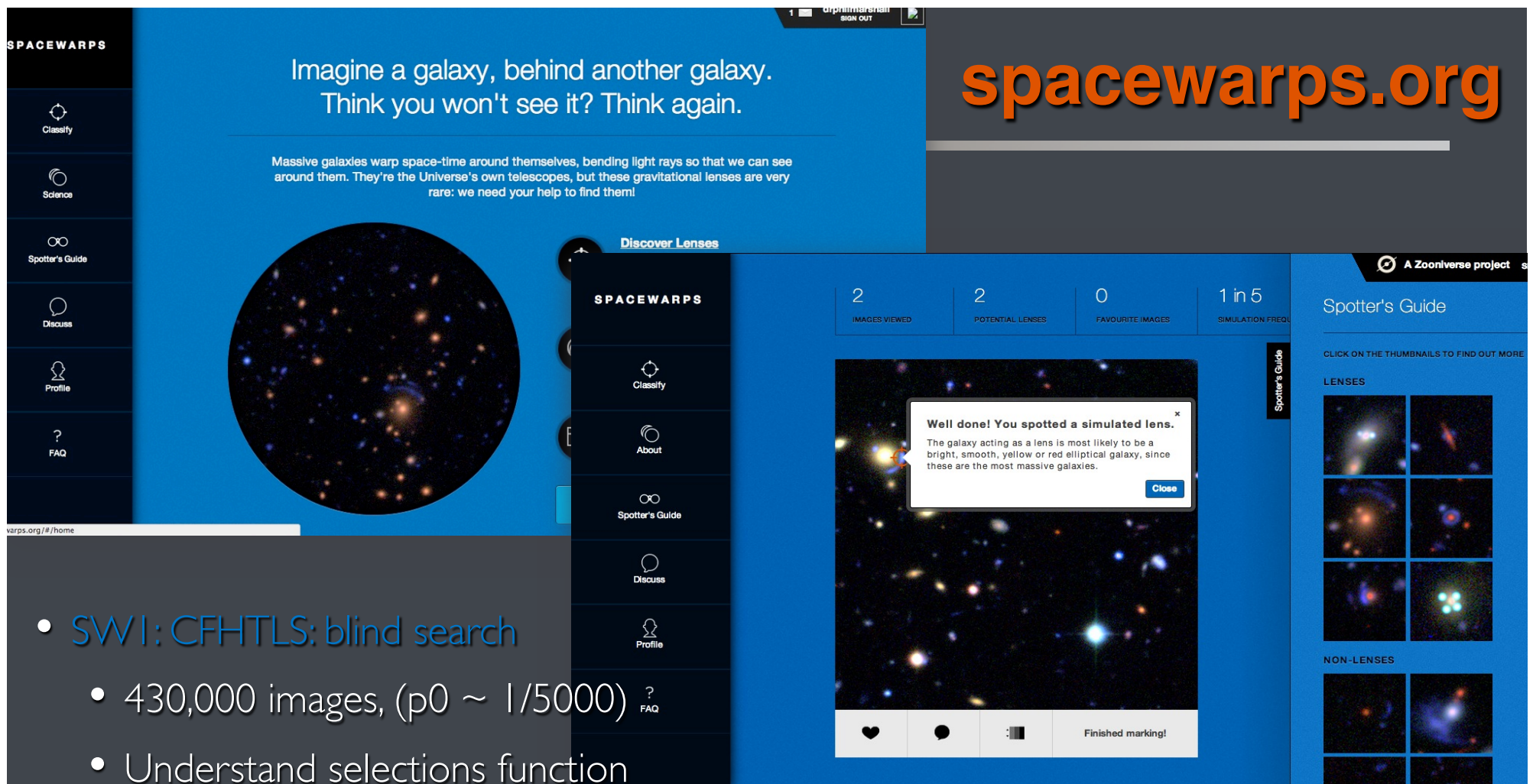
Study explosions on the Sun

Explore interactive diagrams to learn about the Sun and the spacecraft monitoring it.



Find planets around stars

Lightcurve changes from the Kepler spacecraft can indicate transiting planets.



- SWI: CFHTLS: blind search

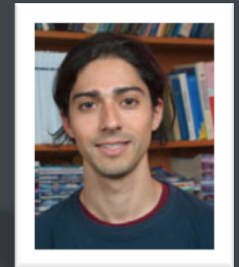
- 430,000 images, ($p_0 \sim 1/5000$)
- Understand selections function
- Improve automated algorithms
- Rare objects: lensed quasars, unusual/exotic (faint, red, odd-shaped...)
 - arcs in optimized color composite images
- Training set of "sims" and "duds" used to teach volunteers what to look for, and what to ignore

SPACE WARPS Collaboration

SPACE WARPS SCIENCE TEAM:

PIs: Phil Marshall (KIPAC Stanford) Anupreeta More (IPMU)
Aprajita Verma (Oxford)

Elisabeth Baeten,* Claude Cornen,* Thomas Jennings,* Rafi Kueng
(Zurich), Christine MacMillan,* Surhud More (IPMU), Julianne Wilcox,*
Layne Wright,* Prasenjit Saha (Zurich), Matthias Tecza (Oxford)



SPACE WARPS DEVELOPMENT TEAM:

Amit Kapadia, Chris Snyder, Michael Parrish, David Miller, Arfon
Smith, Kelly Borden (Zooniverse/Adler Planetarium), Rob Simpson,
Chris Lintott (Oxford)

VICS82 SURVEY TEAM:

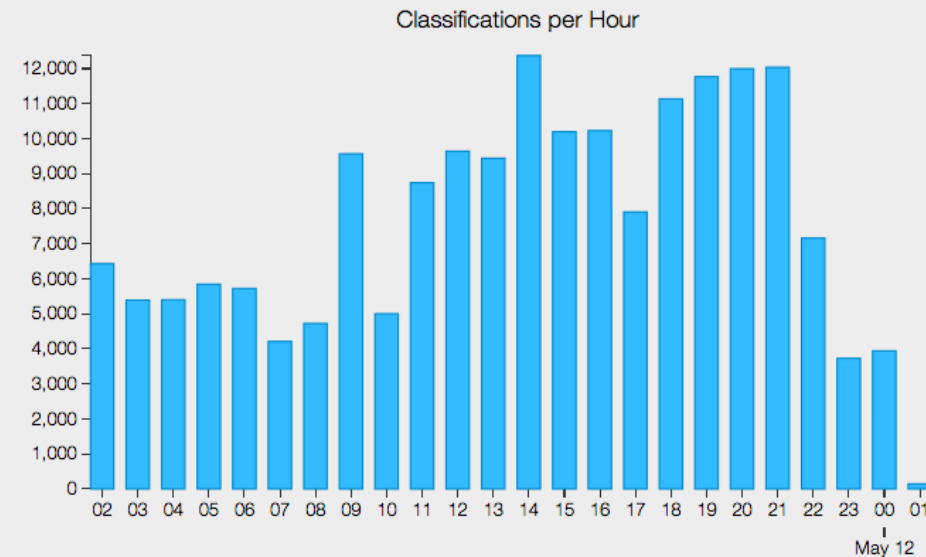
Jim Geach (Herts), Jean-Paul Kneib (EPFL), Yen-Ting Lin, Martin
Makler (CBPF), Eli Rykoff & Eduardo Rozo (KIPAC)



CLASSIFICATIONS

1,365,646

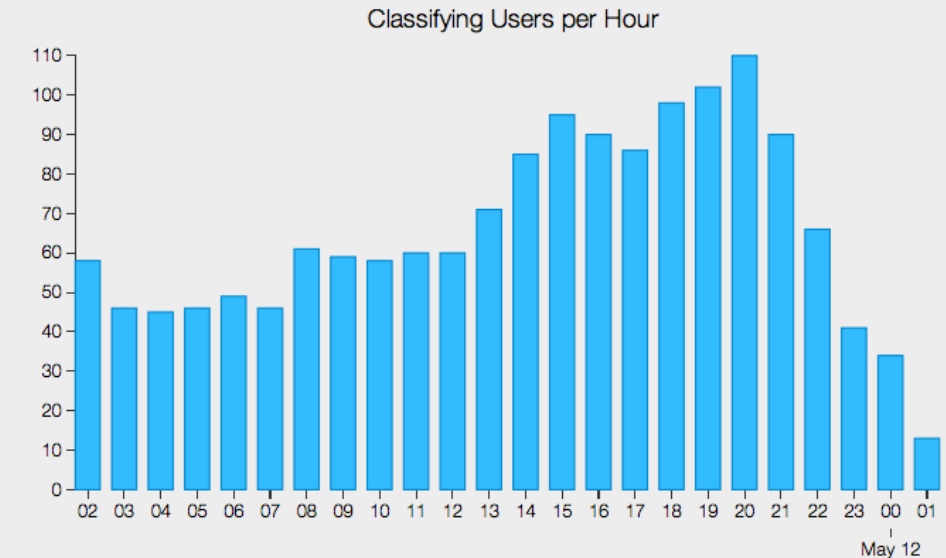
Total



USERS

5,641

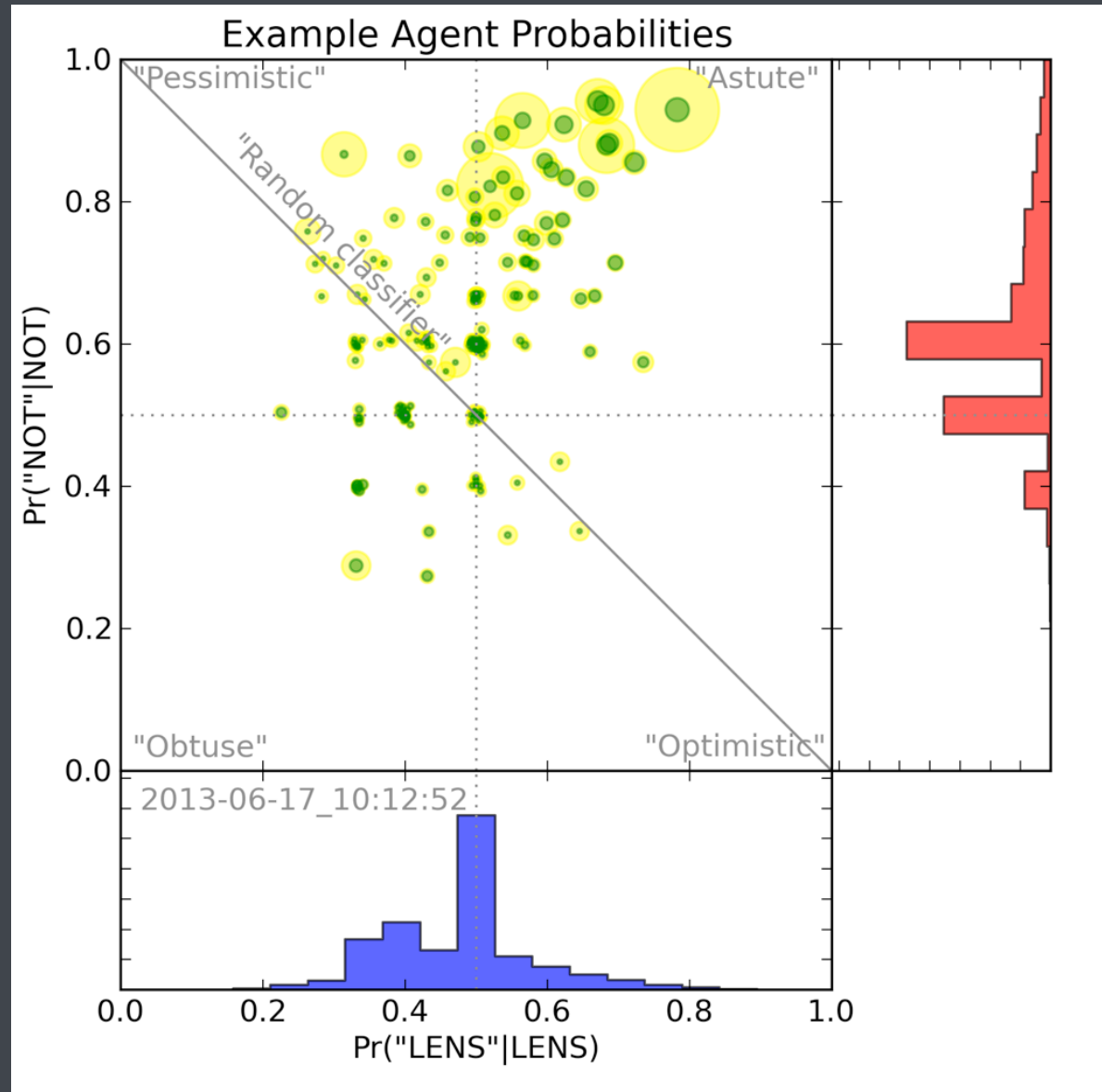
Total



- 2 million image classifications in first week (10k per hour), 11 million over 6 months
- Collaboration of over 60,000 citizen scientists, but typically only ~10-100 active at a time

SWAP: Making sense of the markers

- ★ Assign each volunteer a software **Agent**, which: listens to its volunteer classifying images as “LENS” or “NOT” by marking (or not)
- ★ Each Agent tries to describe its volunteer with just two numbers:
 - ★ $\Pr(\text{“LENS”}|\text{LENS})$
 - ★ $\Pr(\text{“NOT”}|\text{NOT})$
- ★ Agent updated each time a training image is classified
- ★ Encodes all our assumptions; Humans are complex, Agents are simple
- ★ Errors: mistake classifications, our interpretation

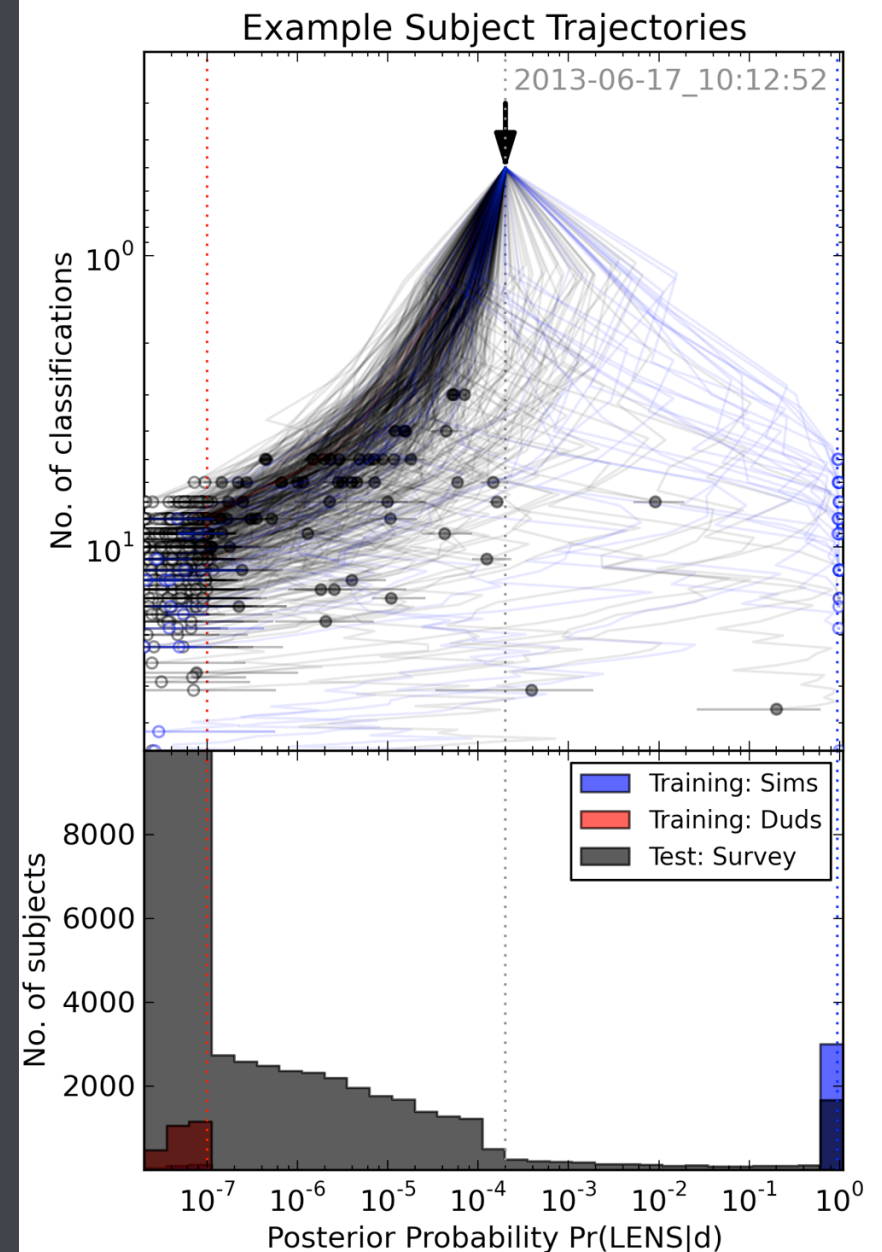


SWAP: Making sense of the markers

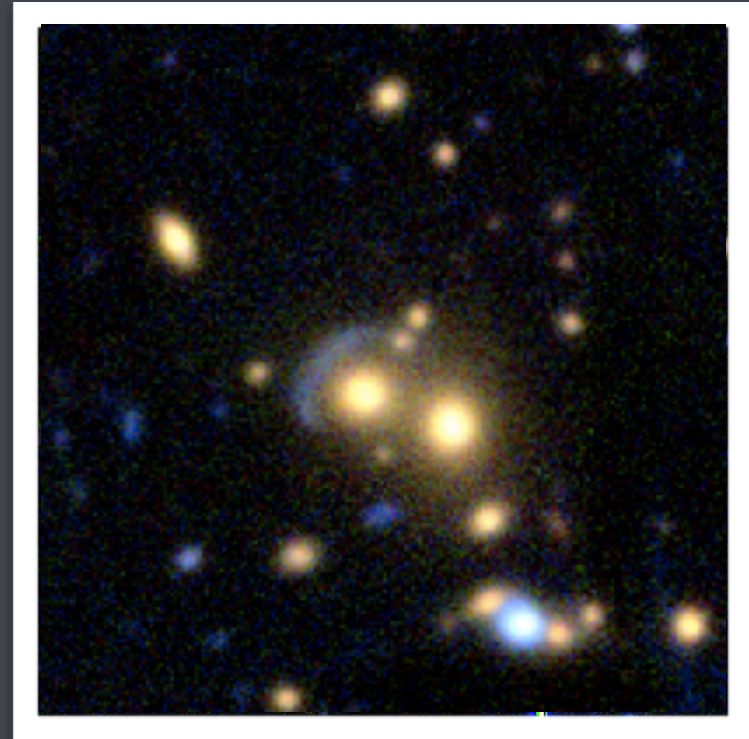
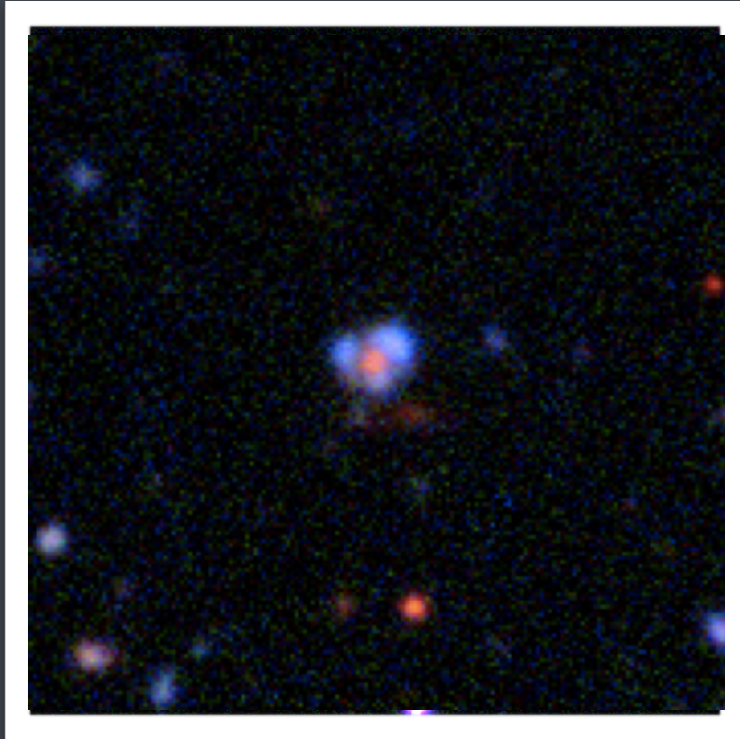
- ★ Agents update the posterior probability
- ★ $\Pr(\text{LENS}|\text{d})$ for each survey image (“subject”) as it is seen, in an online inference

$$\Pr(\text{LENS}|C_k, T_k) = \frac{\Pr(C_k|\text{LENS}, T_k) \cdot \Pr(\text{LENS})}{[\Pr(C_k|\text{LENS}, T_k) \cdot \Pr(\text{LENS}) + \Pr(C_k|\text{NOT}, T_k) \cdot \Pr(\text{NOT})]} \quad (\text{A4})$$

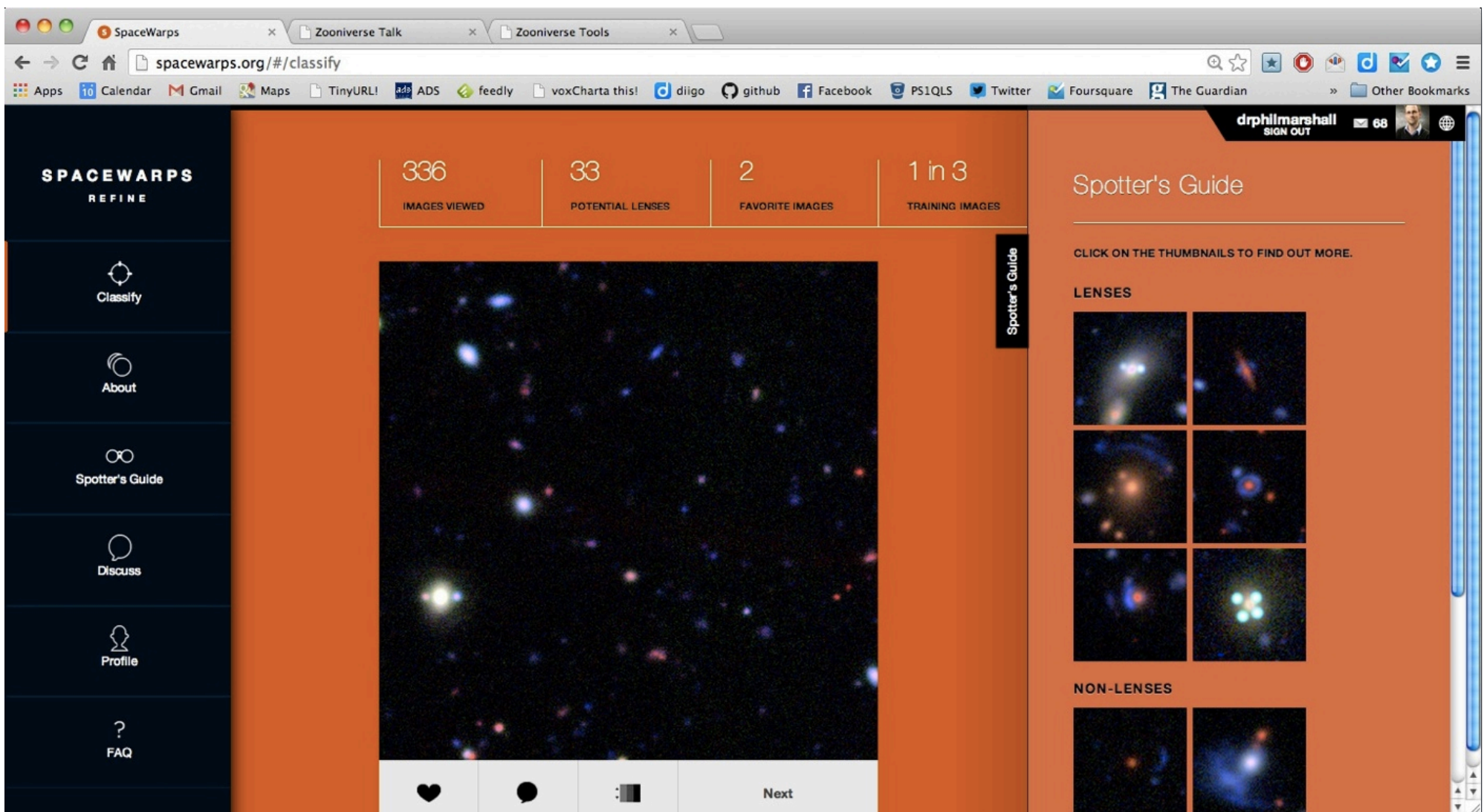
- ★ Below $p=10^{-7}$, subjects are retired from the stream
- ★ Above $p=0.95$, subjects are labelled “candidates”
- ★ ~ 10 classifications needed per rejection



CFHT-LS Stage I Results

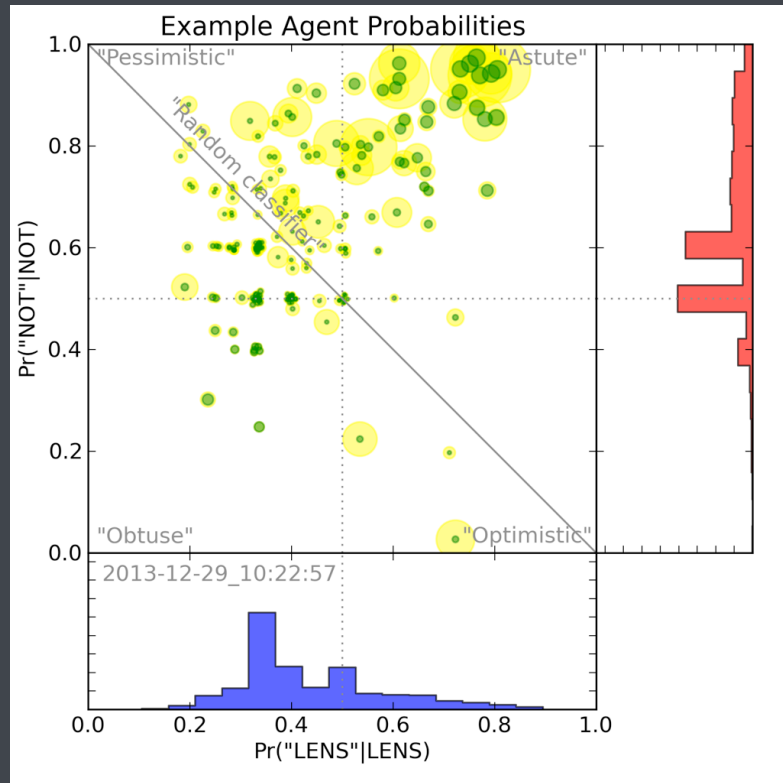


- Completeness (to sims) is 93%, with missing 7% understandably non-visible
- Some good candidates identified: galaxy-scale systems that would fail an LRG cut, faint group-scale arcs
- ~338 I candidates, out of 430,000 images (99.2% rejections)

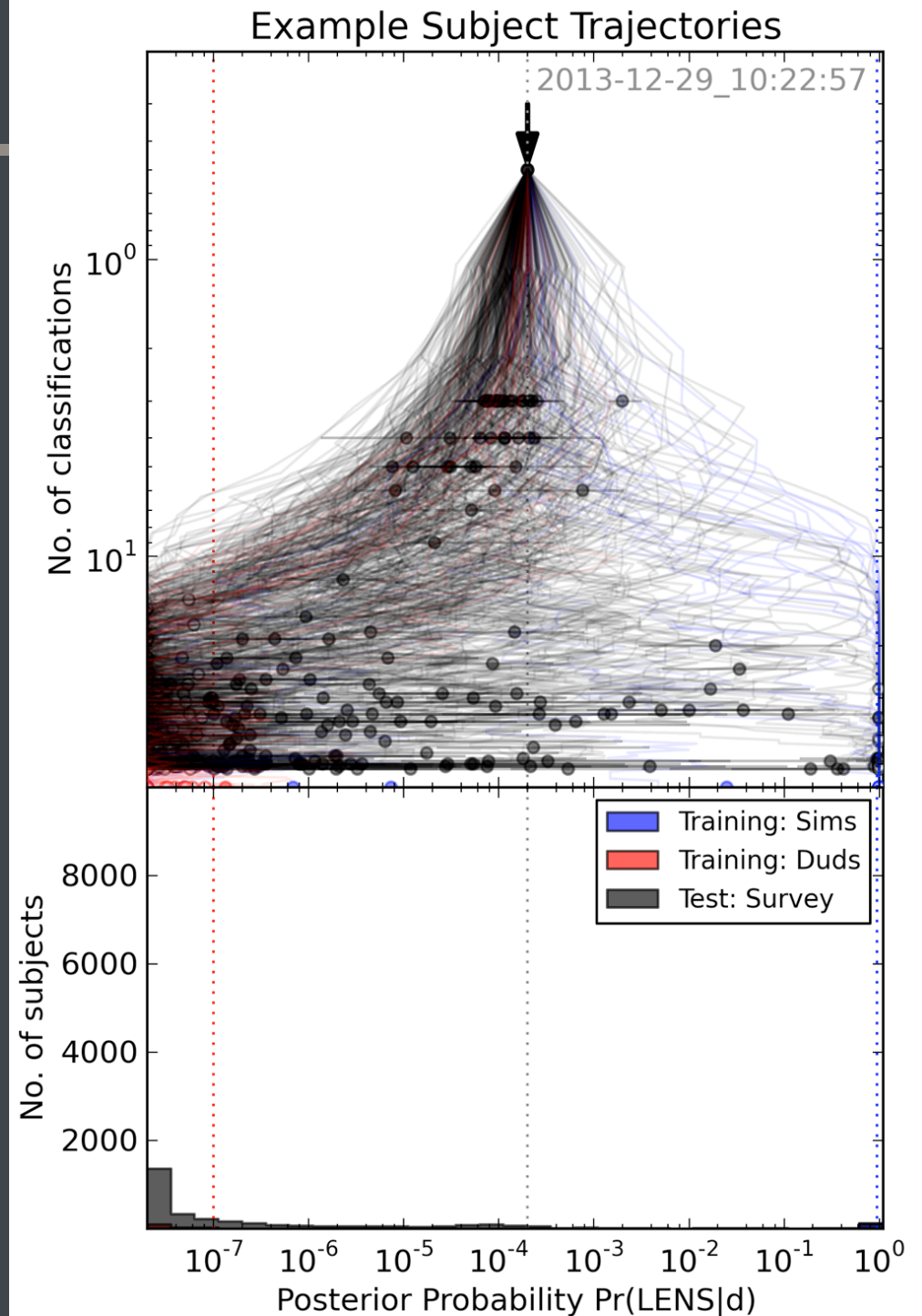


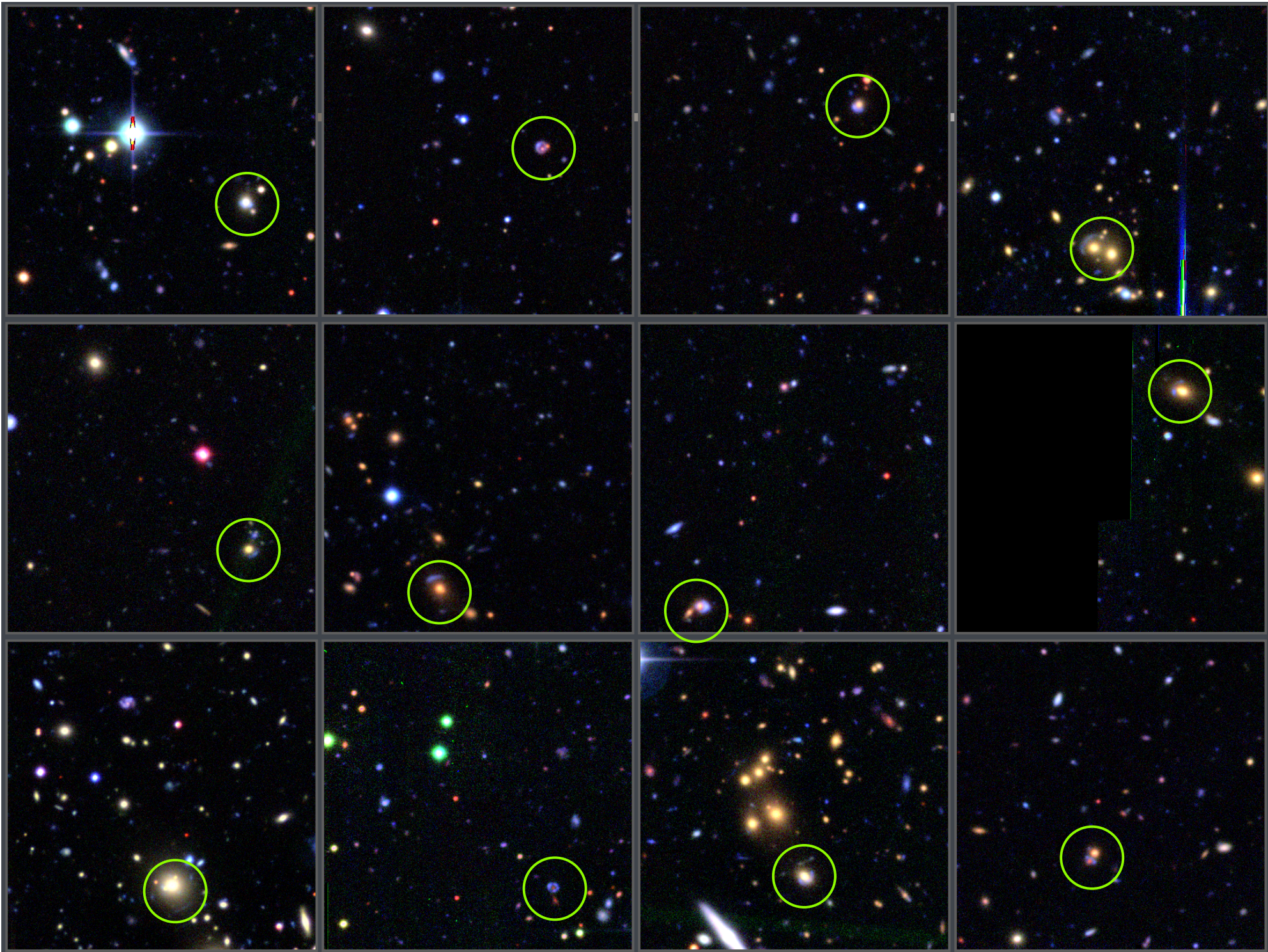
- Stage 2 sample “refinement:” science team reconfigured website (via github), painted it orange
- New “harder” training set with feedback, sims & false positives

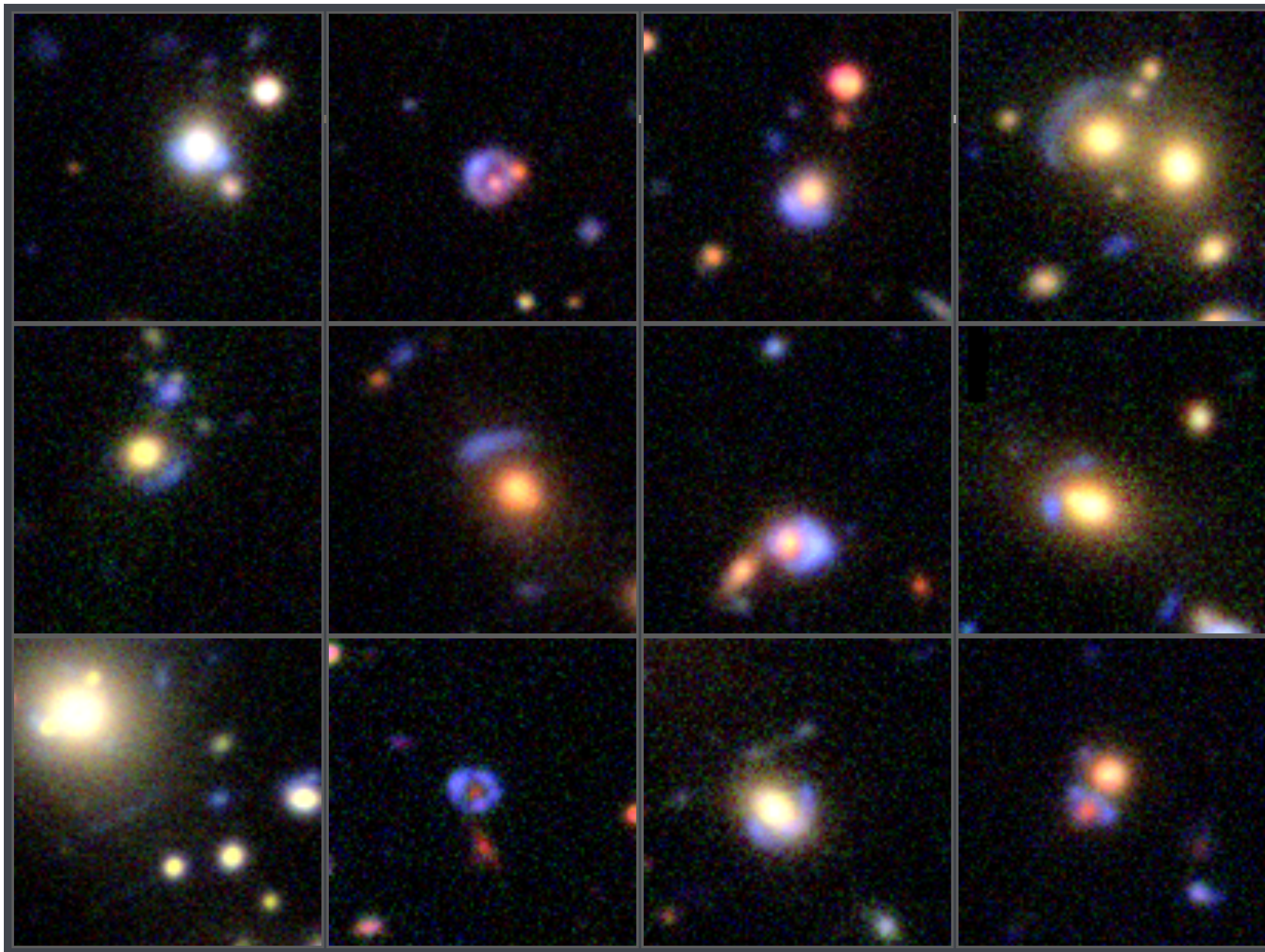
Stage 2 First Results



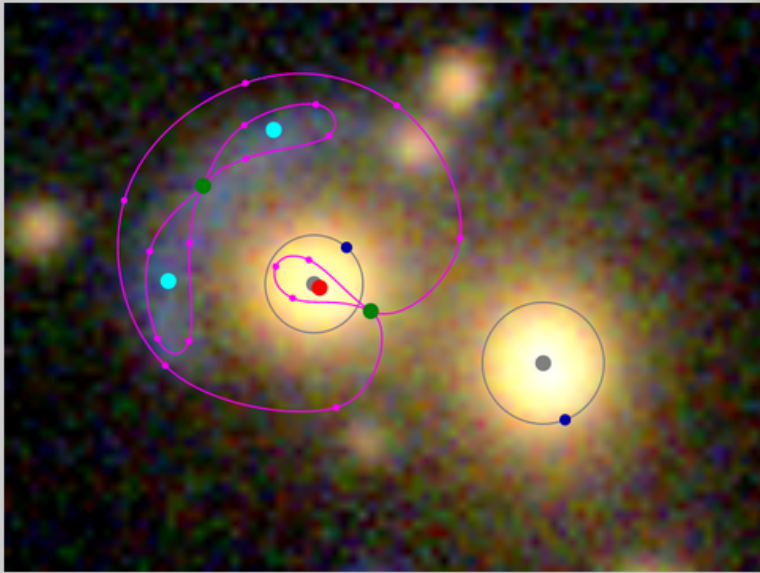
- Ranked list of candidates by P
- Completeness (in harder sims) is 78%
- "Expert" inspection of top 600
- ~60 new lens candidates








Citizen Lens Modelling

Input Image


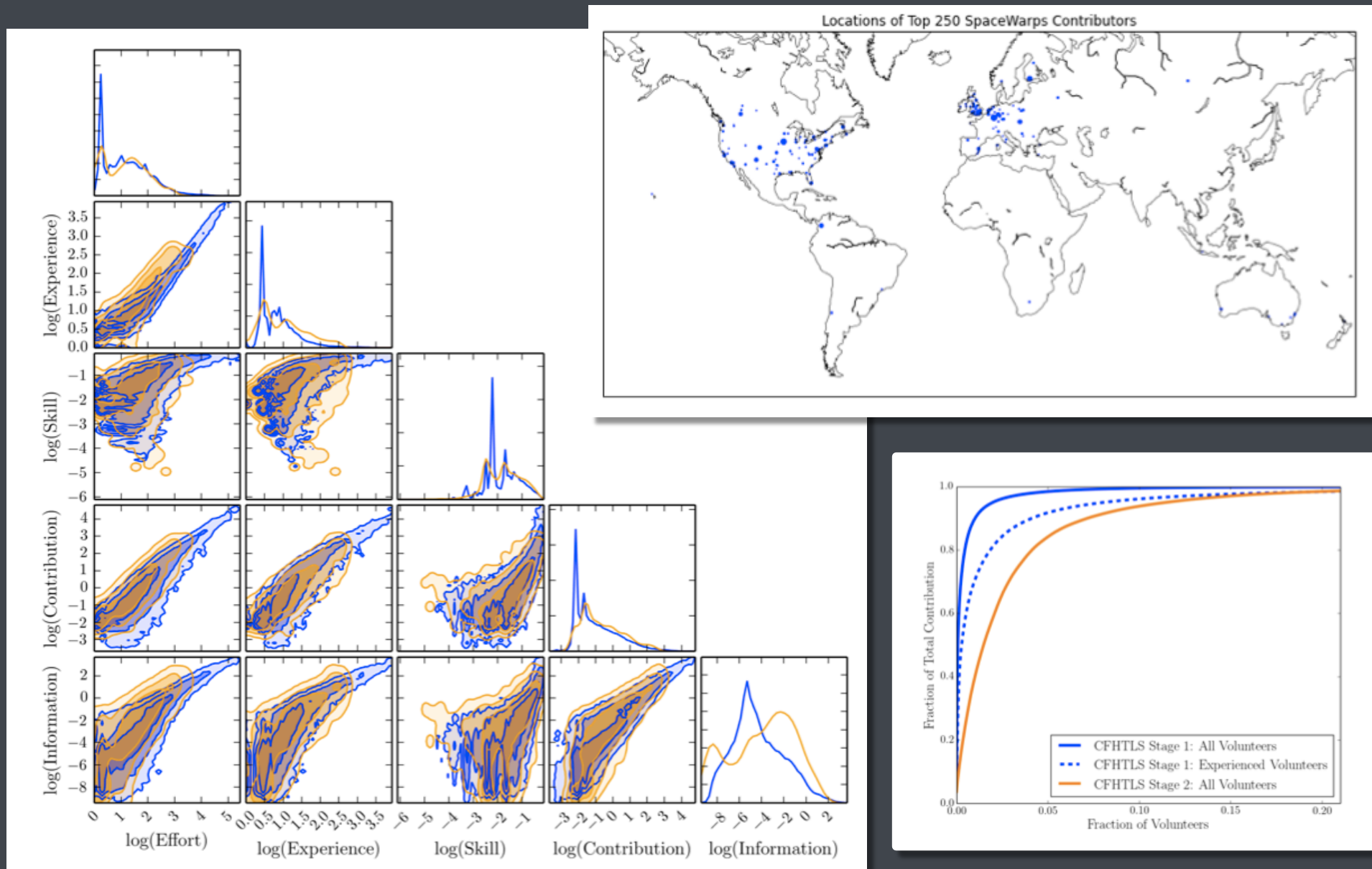
Synthetic Image


> actions: [click to hide]

Revise this result	↶	Start from scratch	↶
see parent model by Phil 2013-08-26 17:55	↶	see revision by ElisabethB 2013-08-26 22:00	↶
see revision by c_cld 2013-08-30 18:27		↶	

“SpaghettiLens”
Kueng et al. MNRAS submitted

Understanding the crowd



Chris Davis, Michael Baumer, Phil Marshall

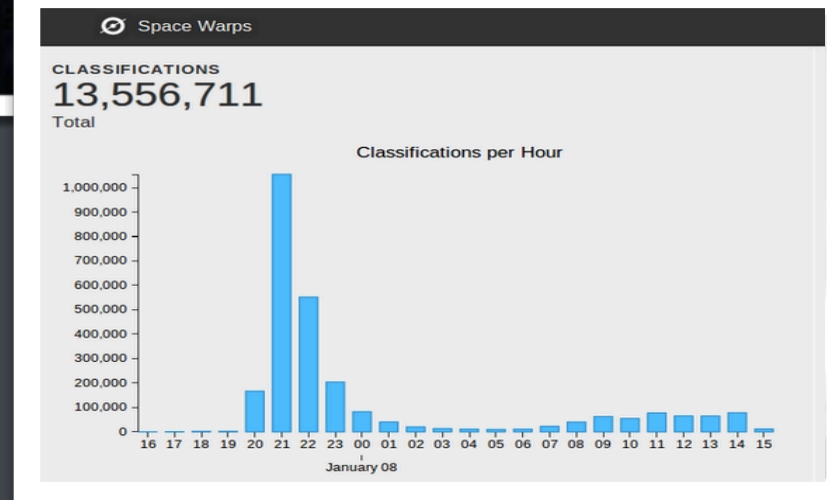
SPACE WARPS 2: VICS82

40,000 “targets” selected from SDSS++

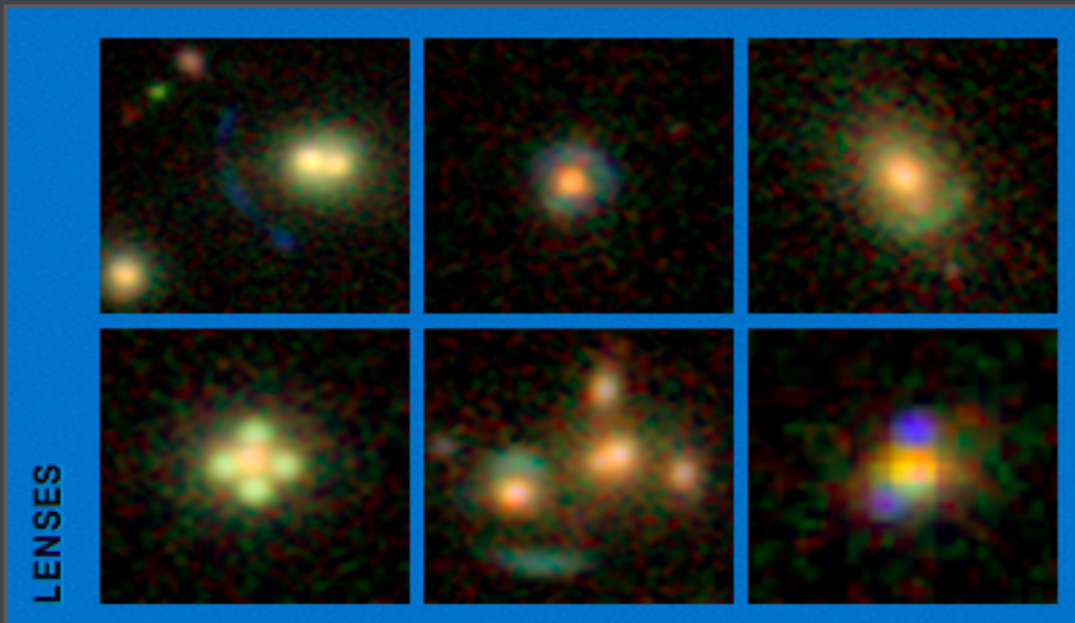
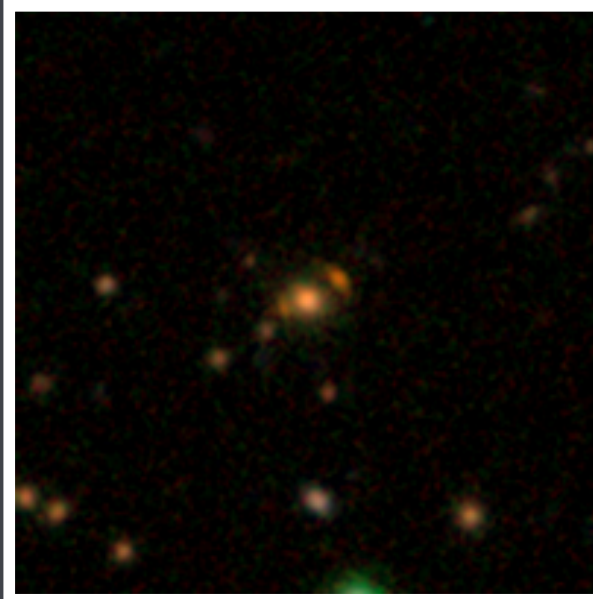
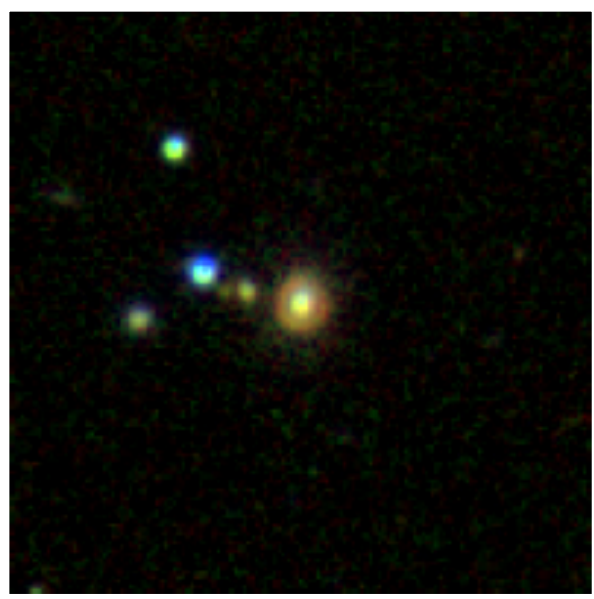
iJKs images, sims generated as for CFHTLS, color scales chosen for maximum contrast



Launched on BBC Stargazing Live TV programs
1 million image classifications in the single hour after
the first Stargazing Live show finished



SPACE WARPS 2: Initial Results



- The 3 candidates have red arcs - despite the training sims only having blue/green arcs
- Space Warps is more than just a supervised learning system ... classifiers have imagination and intuition

SPACE WARPS 1 & 2: Conclusions & Future

- ★ Crowd-sourced lens detection successful (targeted and blind)
 - ★ 90% complete (to sims) , 99% rejection
 - ★ Find *exotic or tricky* lens candidates missed by robots
- ★ Crowd are *imaginative, intuitive and adaptable*
- ★ Crowd like to 'Talk' and to 'Learn', motivated by contribution to science
- ★ Media fuelled classification frenzy (SW2): 10^6 classifications per hour – *LSST 20,000 sq deg in 40 days!* (cf SW1 max 10k/h 11y)
 - ★ How to maintain momentum? New unseen data, LSST-TV support language and time zones
 - ★ Focus on sub-samples: *large-scale QC inspection* of robot candidates (targeted)

SPACE WARPS 1 & 2: Conclusions & Future

- ✦ Completed first system & results papers
 - ✦ (Marshall, AV, More et al, More, AV, Marshall et al., Geach, More, AV et al.)
 - ✦ comparisons: humans vs robots, supervised vs unsupervised learning
 - ✦ analysing the Bureau: Where is the information coming from?
- ✦ COMING SOON: watch out for **SPACE WARPS 3** in the autumn & more....
- ✦ **SW3+**: Interest from KiDS, **DES (SW3)**, PSI, HSC, (VIDEO) ...
- ✦ Space Warps Labs to port **modeling to the crowd**
- ✦ Euclid & LSST ...